



The  
University  
Of  
Sheffield.

**MAS 6360**

**SCHOOL OF MATHEMATICS AND STATISTICS**

**Spring Semester 2015–2016**

**Geometry I**

**2 hours 30 minutes**

*Attempt all the questions. The allocation of marks is shown in brackets.*

*Throughout the paper  $I$  denotes an identity matrix and  $J$  denotes a matrix of the form  $\begin{bmatrix} 0 & I \\ -I & 0 \end{bmatrix}$ . The standard symplectic form  $\Omega$  on  $\mathbb{R}^{2n}$  is defined by  $\Omega(Z, Z') = Q \cdot P' - P \cdot Q'$ , where  $Z = (Q, P)$  and  $Z' = (Q', P')$  are elements of  $\mathbb{R}^{2n}$ .*

- 1 (i) Let  $S$  be a  $2n \times 2n$  matrix (with real entries). Define what it means for  $S$  to be a *symplectic matrix*.

Now write  $S$  in block form as

$$S = \begin{bmatrix} A & B \\ C & D \end{bmatrix}$$

where  $A, B, C, D$  are  $n \times n$  matrices. Show that  $S$  is symplectic if and only if all the following hold

$$A^T C = C^T A, \quad B^T D = D^T B, \quad A^T D - C^T B = I.$$

**(4 marks)**

- (ii) Suppose that  $S \in Sp(2n)$  has a real eigenvalue  $\lambda$  with a corresponding eigenvector  $Z \in \mathbb{R}^{2n}$ . Show that  $JZ$  is an eigenvector for  $S^T$  and find the corresponding eigenvalue. **(4 marks)**

- (iii) Let  $(V, \omega)$  be a symplectic vector space of dimension  $2n$ . Define the concept of *symplectic basis* for  $(V, \omega)$ .

Now consider the symplectic vector space  $(\mathbb{R}^{2n}, \Omega)$ . Let  $e_1, \dots, e_n$  be any orthonormal basis in  $\mathbb{R}^n$ . Prove that

$$(e_1, 0), \dots, (e_n, 0), (0, e_1), \dots, (0, e_n)$$

is a symplectic basis in  $\mathbb{R}^{2n}$ .

**(8 marks)**

- (iv) Take  $X \in \mathbb{R}^3$  and  $Y \in \mathbb{R}^3$  with  $|X| = 1$  and  $X \cdot Y = 0$ . You are given that

$$V := \{(\xi, \eta) \in \mathbb{R}^6 \mid X \cdot \xi = 0, \quad X \cdot \eta + \xi \cdot Y = 0\}.$$

is a symplectic subspace of  $(\mathbb{R}^6, \Omega)$ .

- (a) Let  $X, B_2, B_3$  be an orthonormal basis for  $\mathbb{R}^3$  containing  $X$ , and write  $Y$  with respect to this basis as  $Y = y_2 B_2 + y_3 B_3$ .

In terms of coordinates with respect to this basis, write down the conditions that  $(\xi, \eta) \in \mathbb{R}^3 \times \mathbb{R}^3$  belong to  $V$ .

For  $(\xi, \eta), (\xi', \eta') \in V$ , express  $\Omega((\xi, \eta), (\xi', \eta'))$  in terms of these coordinates.

Find a symplectic basis for  $V$  in terms of  $X, B_2, B_3$ .

- (b) Now assume that  $Y = 0$ . Show that the subspace

$$L = \{(\xi, \eta) \in V \mid \xi = \eta\}$$

is Lagrangian in  $V$  and find another Lagrangian subspace  $L'$  of  $V$  such that  $V = L \oplus L'$ , proving the stated properties.

**(16 marks)**

**2** (i) Let  $W$  be a vector space of dimension  $k$ .  
 Define the *dual space*  $W^*$ , being sure to include definitions of the vector space operations. State, without proof, the dimension of  $W^*$ . **(6 marks)**

(ii) Let  $(V, \omega)$  be a symplectic vector space of dimension  $2n$  and let  $L_1$  and  $L_2$  be Lagrangian subspaces such that  $V = L_1 \oplus L_2$ .  
 Define a map  $\Phi: L_1 \rightarrow L_2^*$  by  $(\Phi(v_1))(v_2) = \omega(v_1, v_2)$  for  $v_1 \in L_1$  and  $v_2 \in L_2$ . State why  $\Phi$  takes values in  $L_2^*$  and show that it is a linear map.  
 Prove that  $\Phi$  is an isomorphism of vector spaces, stating clearly any general result of linear algebra which you use. **(12 marks)**

**3** (i) Snell's Law may be given as  $n' \sin \theta' = n \sin \theta$  for refraction across a boundary between mediums with indexes of refraction  $n$  and  $n'$ , where  $\theta$  and  $\theta'$  are the angles made by the rays with the normal to the boundary.  
 Derive Snell's Law in vector form so that it applies to rays in  $\mathbb{R}^3$ , including a simple diagram in your answer. Your answer should be in terms of unit vectors  $v$  and  $v'$  along the incoming and outgoing rays, a unit vector  $\Sigma$  normal to the boundary between the two regions, and the indexes of refraction  $n$  and  $n'$ . **(10 marks)**

(ii) (a) Calculate the matrix product

$$\begin{bmatrix} I & w'I \\ 0 & I \end{bmatrix} \begin{bmatrix} I & 0 \\ M & I \end{bmatrix} \begin{bmatrix} I & wI \\ 0 & I \end{bmatrix}$$

where  $M$  is symmetric, and describe the optical situation which leads to finding the product of these matrices. **(12 marks)**

(b) Let  $S \in Sp(4)$  be given in block form by  $\begin{bmatrix} A & B \\ C & D \end{bmatrix}$ . Suppose that there are real numbers  $w, w' > 0$  such that

$$A - I = w'C, \quad D - I = wC.$$

Assuming that  $C$  is invertible, express  $B$  in terms of  $w, w'$  and  $C$ . **(5 marks)**

4 In this question each  $\mathbb{R}^{2n}$  has the standard symplectic form  $\Omega$ .

- (a) Let  $W$  be an  $n$ -dimensional subspace of  $\mathbb{R}^{2n}$ . Take a basis of  $W$  and write the elements as the columns of a  $2n \times n$  matrix which we write in block form as

$$\begin{bmatrix} M \\ N \end{bmatrix}$$

where  $M$  and  $N$  are  $n \times n$  matrices.

Prove that  $W$  is Lagrangian if and only if  $M^T N$  is symmetric. **(4 marks)**

- (b) Let  $L \subseteq \mathbb{R}^{2n}$  be a Lagrangian subspace of  $\mathbb{R}^{2n}$ . Show that it is transverse to both  $\mathbb{R}^n \times 0$  and  $0 \times \mathbb{R}^n$  if and only if it has a representation as in (a) of the form  $\begin{bmatrix} M \\ I \end{bmatrix}$  with  $M$  invertible. **(8 marks)**

- (c) Let  $L$  and  $L'$  be Lagrangian subspaces which are both transversal to  $\mathbb{R}^n \times 0$  and  $0 \times \mathbb{R}^n$ . State without proof the theorem which gives criteria for the existence of  $S \in Sp(2n)$  such that  $S(\mathbb{R}^n \times 0) = \mathbb{R}^n \times 0$ ,  $S(0 \times \mathbb{R}^n) = 0 \times \mathbb{R}^n$ , and  $S(L) = L'$ . **(3 marks)**

- (d) Let  $L$  be the subspace of  $\mathbb{R}^6$  spanned by the vectors

$$(1, 3, 5, 1, 0, 0), \quad (0, 1, 0, 1, -2, 1), \quad (0, 1, 2, 5, 0, -1).$$

Show that  $L$  is Lagrangian in  $(\mathbb{R}^6, \Omega)$  and that it is transverse to both  $\mathbb{R}^3 \times 0$  and  $0 \times \mathbb{R}^3$ . Represent  $L$  in the form

$$\begin{bmatrix} M \\ I \end{bmatrix}$$

as in (b) and determine the signature of  $M$ . **(8 marks)**

**End of Question Paper**